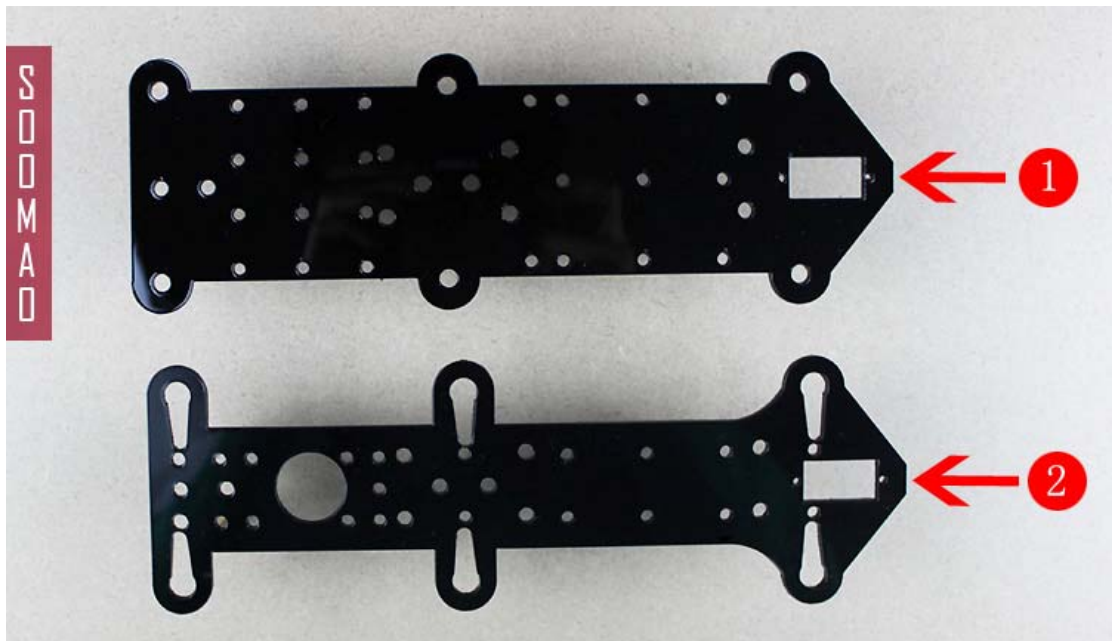
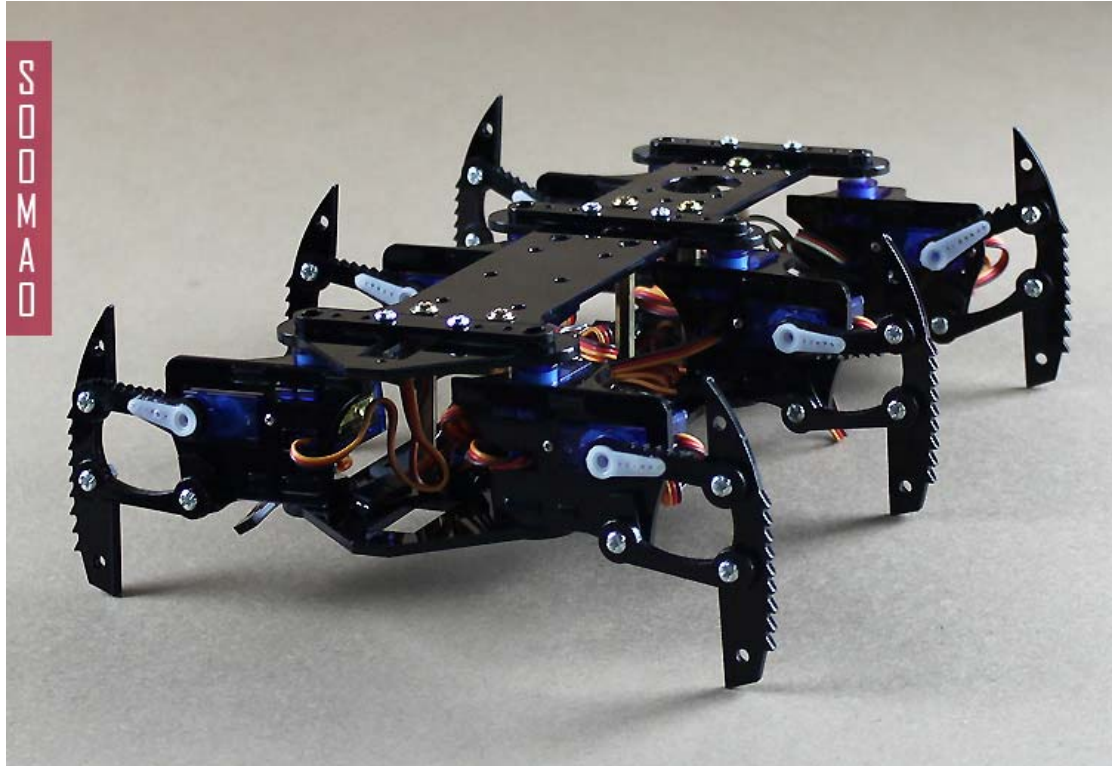




Instruction of installation

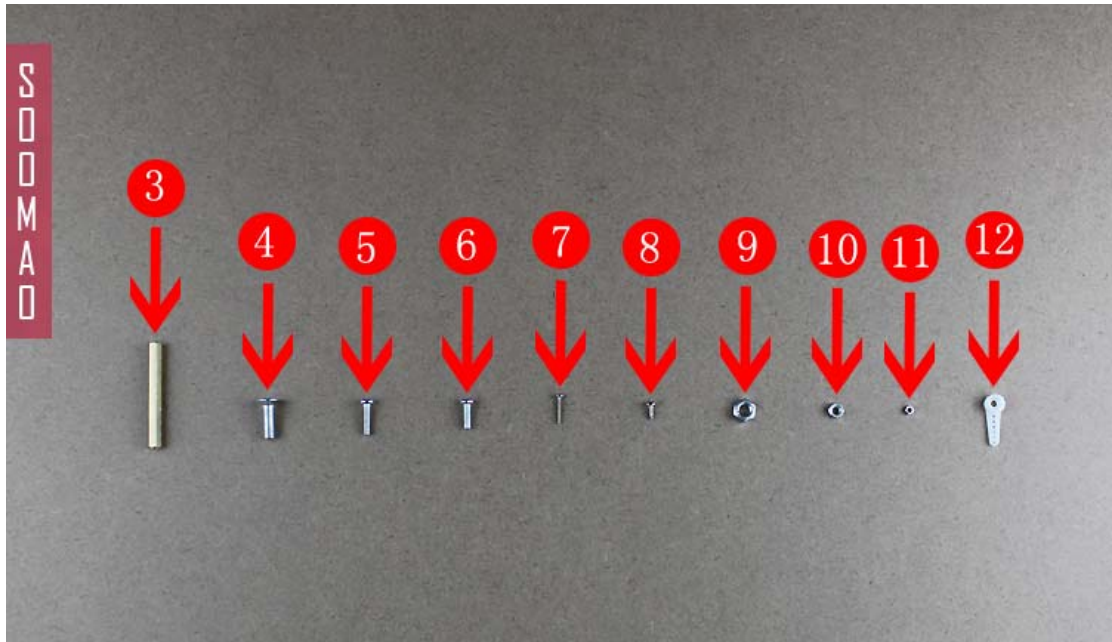


Spare parts introduces 1

The main part of the parts, the two parts of a body is the main part of the.

Part 1: the main body bottom acrylic board x 1.

Part 2: the main body of the top acrylic board x 1.



Spare parts introduces 2

These are composed of 6 legged robot must have hardware components (such as the last servo components).

3:M3 x 5 40mm copper cylinder parts

Part 4: M5 x 6 15mm screws, countersunk head

Part 5: head M3 screws 13mm x 6

Part 6: head screws M3 10mm x 28

Part 7: head M1.5 screws 11mm x 18

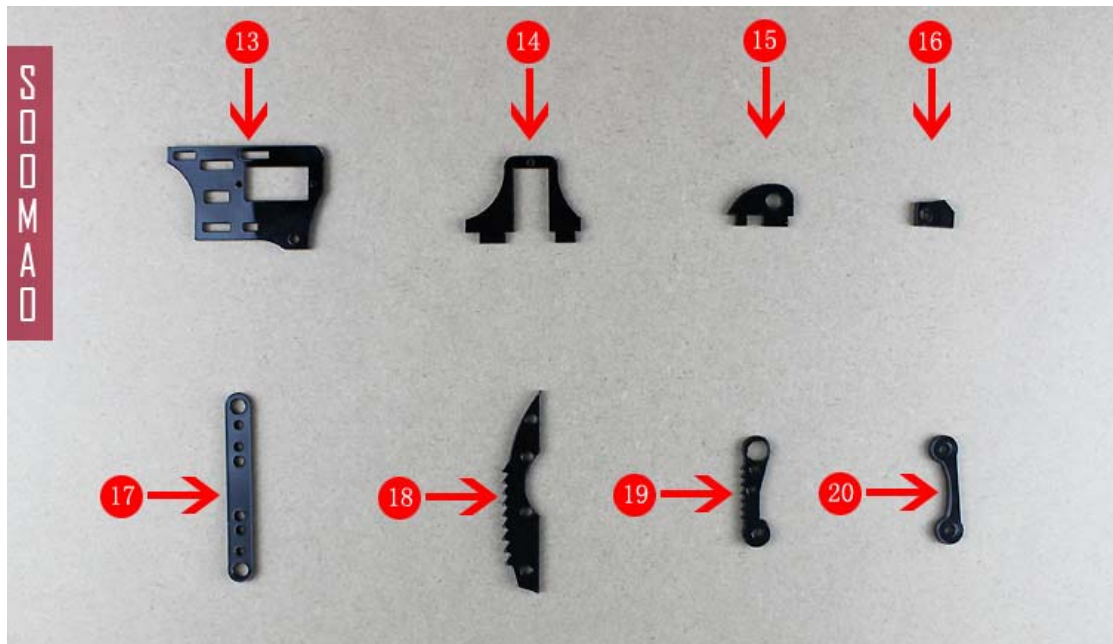
Part 8: head M2 screws 7mm x 24

Parts nut:M5 9 x 6

Parts nut:M3 10 x 34

Parts nut:M1.5 11 x 18

Part 12: actuator accessories x 12



Spare parts introduces 3

Part 13: acrylic component X 6

Part 14: acrylic component X 6

Part 15: acrylic component X 6

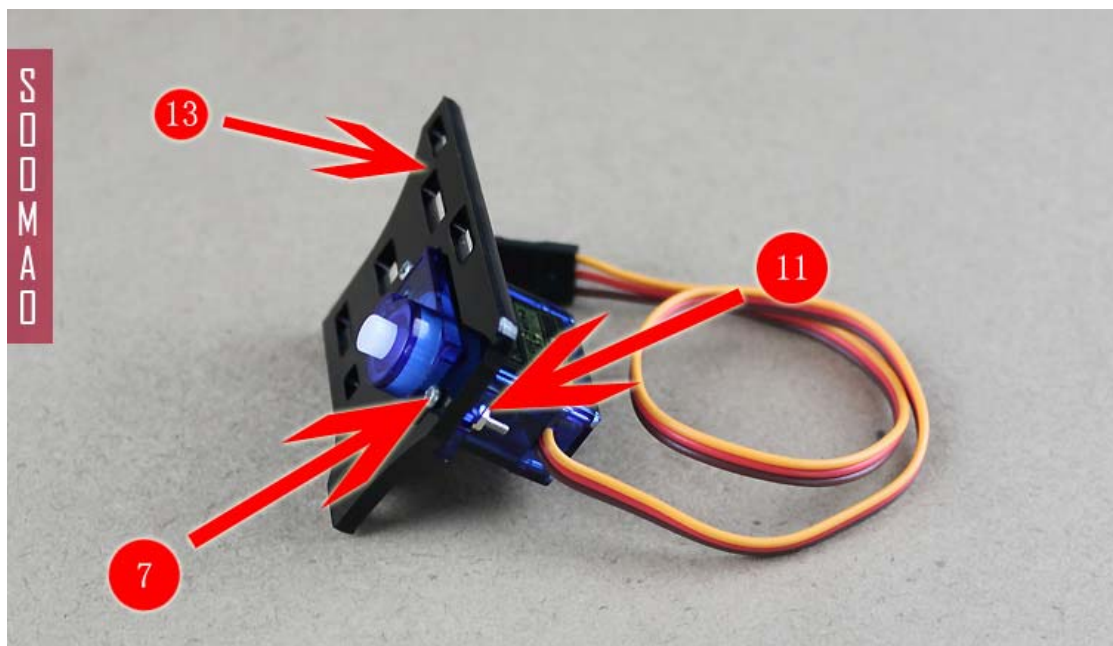
Part 16: acrylic component X 6

Part 17: acrylic component X 3 (at the top)

Part 18: acrylic component X 6

Part 19: acrylic component X 6

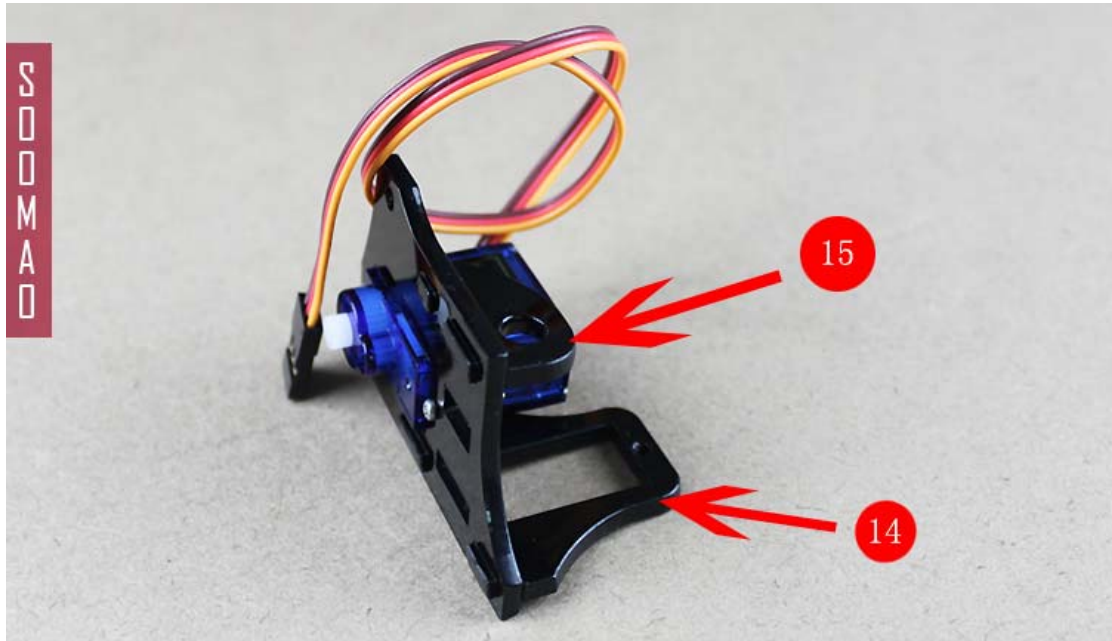
Part 20: acrylic component X 6



Installation steps 1

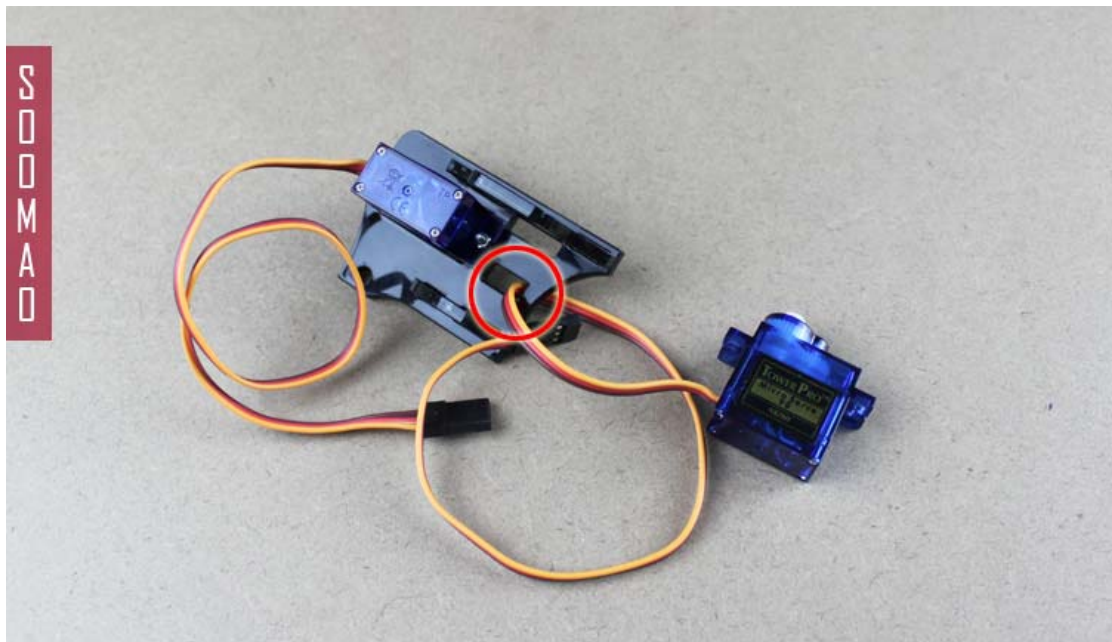


First remove the components 13. Then use the component 11 nuts, screws and parts of the steering gear is fixed on the 7 parts above 13, as shown in.



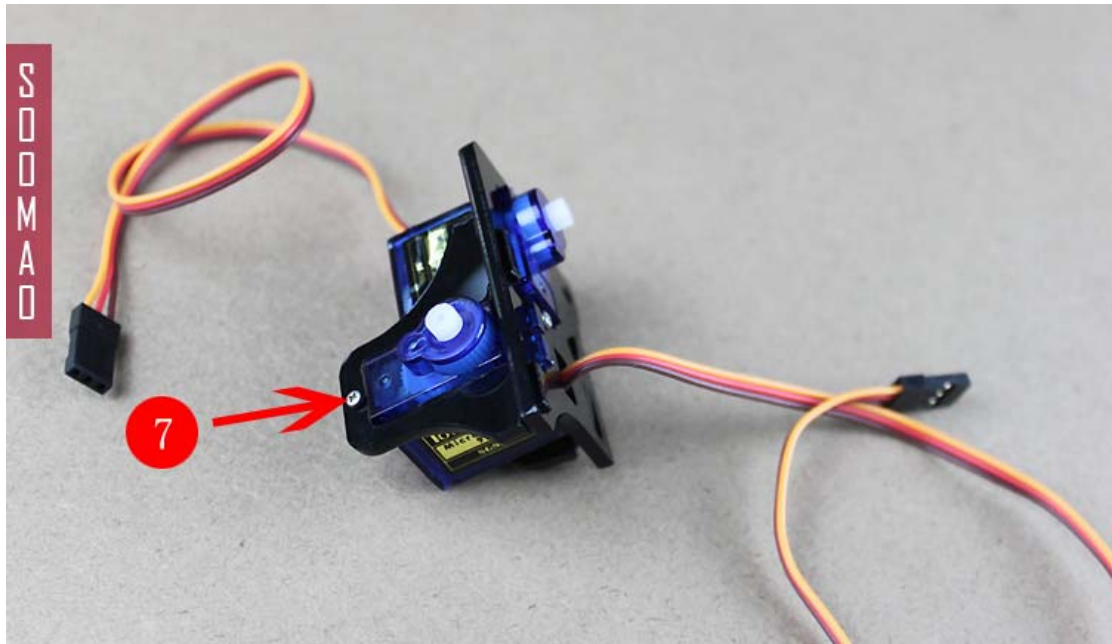
Installation steps 2

Then remove the member 15 and member 14, inserted into the member 13 (please gently insert, not too vigorously. Too vigorously acrylic will squash). The left shown.



Installation steps 3

Take out a new steering gear, steering gear line will figure, through the member 13 hole.



Installation steps 4

Member 7 screws, and the corresponding components of a set of 11 nut, fixed the steering gear.



Installation steps 5

Member 12, member 19 to go into.



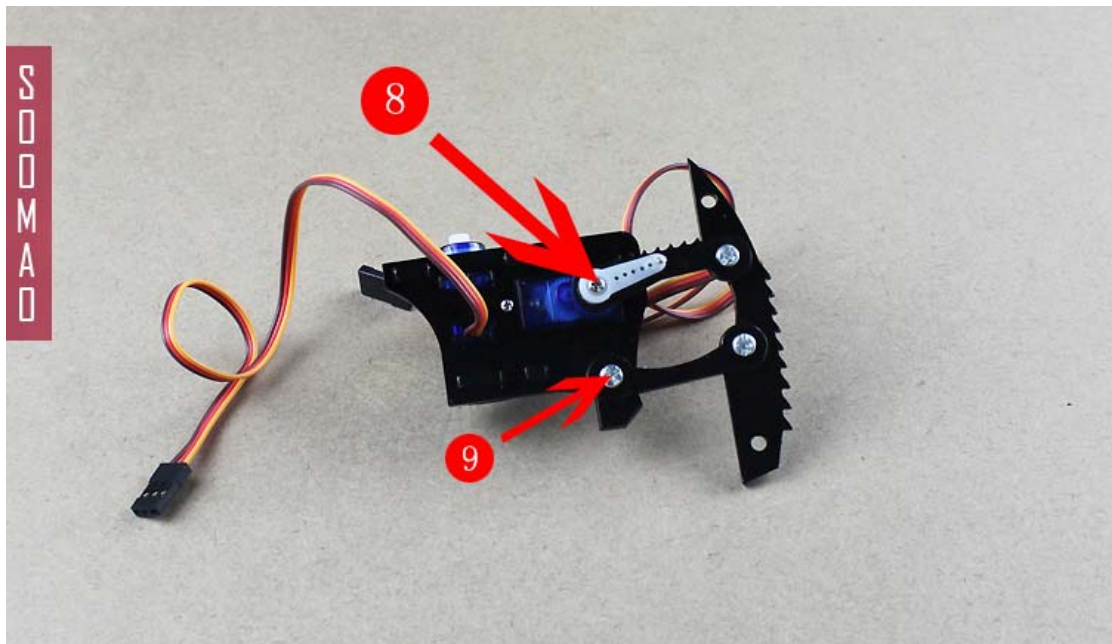
Installation steps 6

In part 8 of the screw, screw.



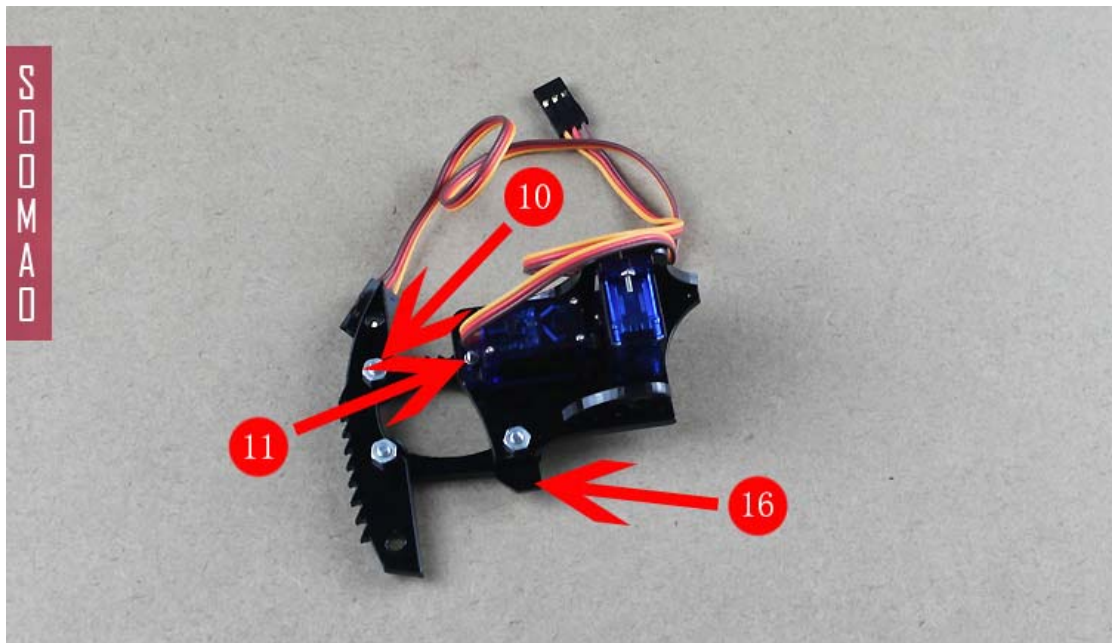
Installation steps 7

Figure, with Part 6 screws and supporting nut, fixed these parts according to the drawing.



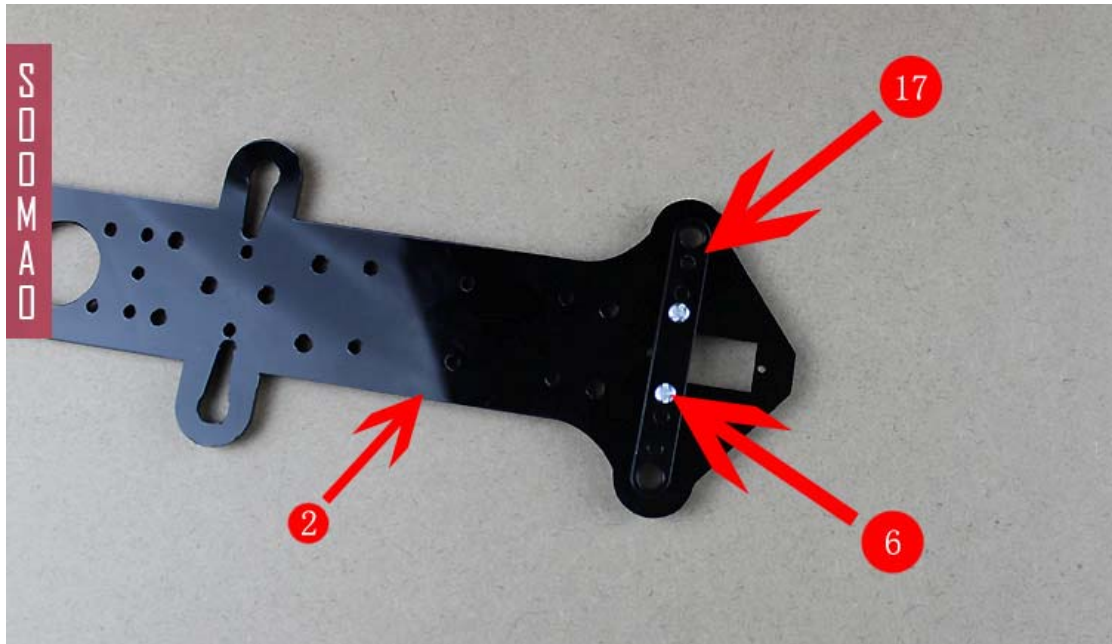
Installation steps 8

Figure, with parts 8 and 9, the installed components.



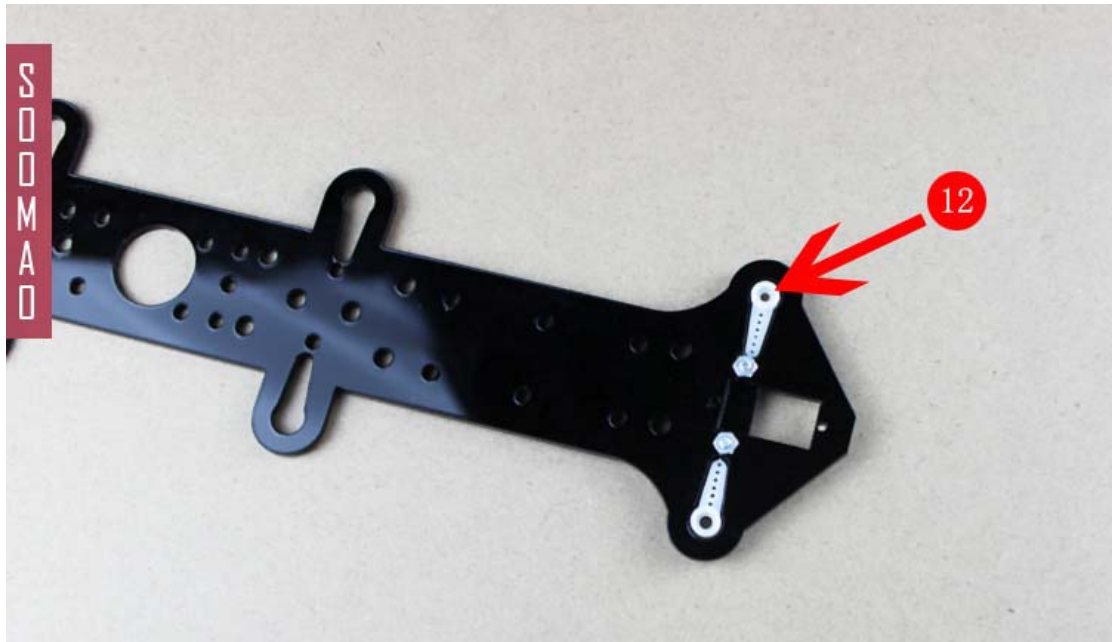
Installation steps 9

Member 16 pad arm, with M3 screws, nuts figure installed other arm.



Installation steps 10

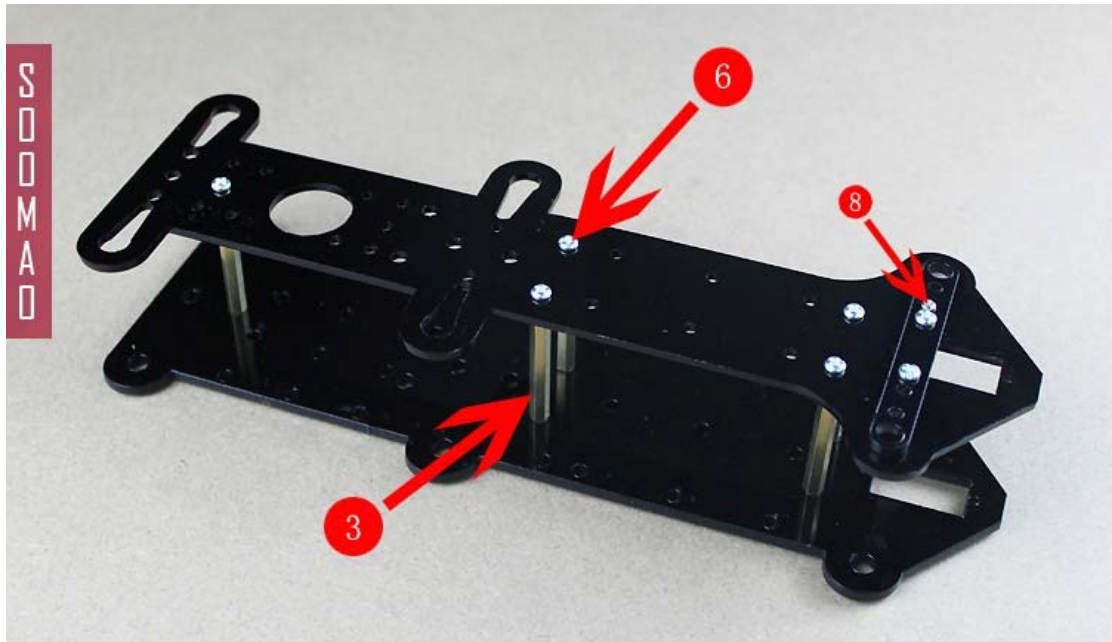
The 17 parts above into 2 parts, the two part tighten the nut member 6 screws and corresponding. Section 17 is 3, corresponding to the large acrylic, 2 parts of the remaining 17 similarly installation.



Installation steps 11

The white part 12 (steering parts) into this place.

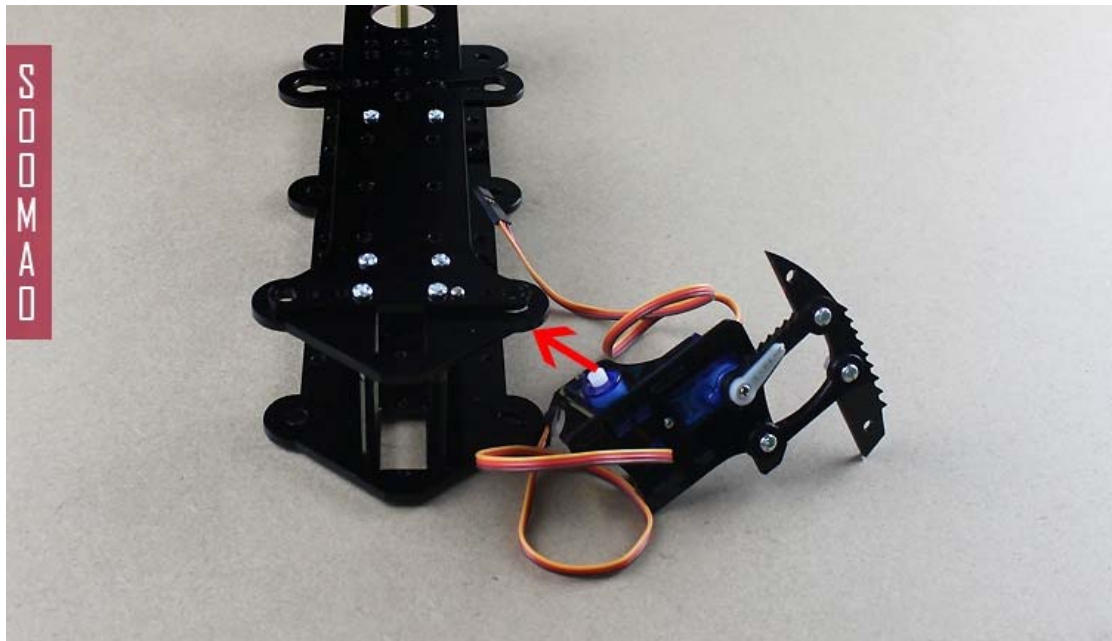




Installation steps 12

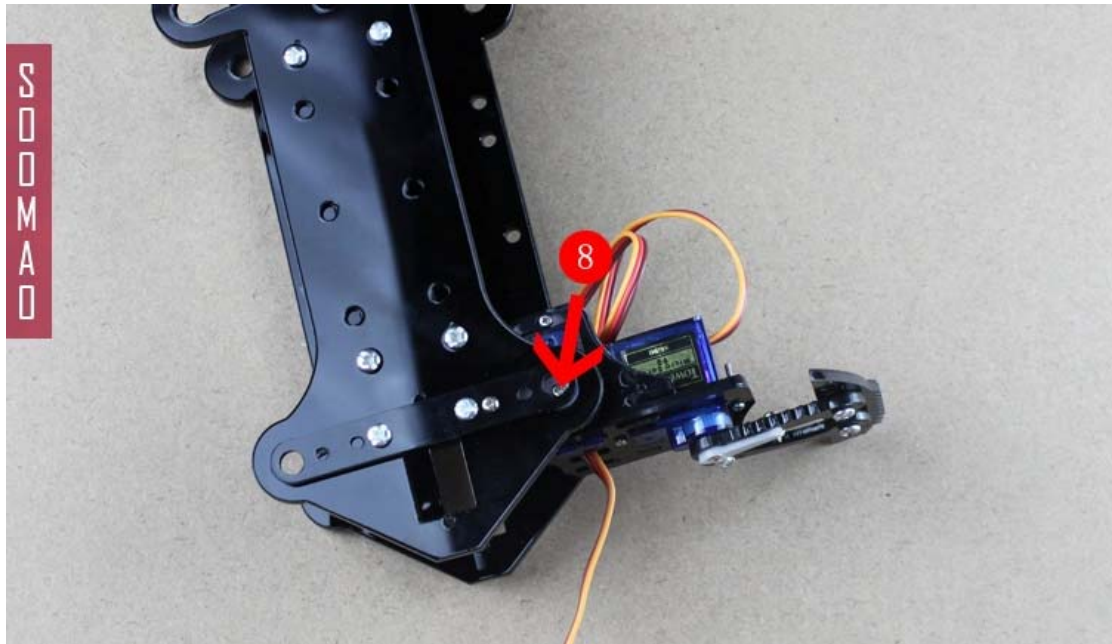
Member 8 screws, tighten a step put good actuator accessories.

Accessories for the 6 and 3 parts, the upper and the lower board installed. A total of 5 pillars.



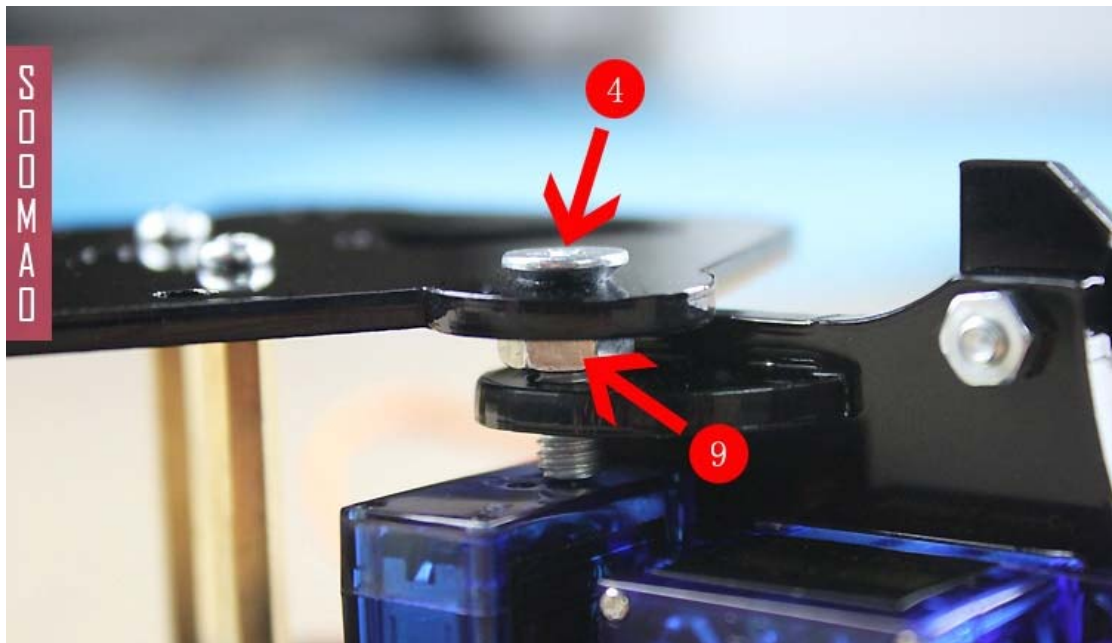
Installation steps 13

The installation will be installed before the pin to figure position.



Installation steps 14

The steering gear on the step of installed components, used to tighten the 8.



Installation steps 15

In part 4 and Part 9, as shown in figure, counter steering gear. This can avoid steering around swing. So far, we have installed a pin, the other pin similarly installed, it completed the installation.